Complex Path Integral Representation for Semiclassical Linear Functionals

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Semiclassical linear functionals are characterized by the distributional equation $D(\phi L) + \psi L = 0$ where ϕ and ψ are arbitrary polynomials with the condition $\deg(\psi) \ge 1$. Two cases are considered:

- (A) $\deg(\phi) > \deg(\psi)$
- (B) $\deg(\phi) \leq \deg(\psi)$.

In an earlier work by the authors (*J. Comput. Appl. Math.* **57** (1995), 239–249) integral representations are given for semiclassical functionals in case (A). Here the problem is continued and case (B) is solved: it is always possible to choose some path γ in the complex plane such that every solution, regular or not, of $D(\phi L) + \psi L = 0$ can be represented in the form $\langle L, p \rangle = \int_{\gamma} w(z) p(z) dz$ where w(z) is a solution of the differential equation $(\phi w)' + \psi w = 0$. In some cases, the expression for *L* is a singular integral and a regularization process is given. © 1998 Academic Press

1. INTRODUCTION

The first authors to study semiclassical orthogonal polynomials were E. N. Laguerre [8] and J. Shohat [18]. Recently, a unified theory of these polynomials has been developed by P. Maroni in [11, 13, 14], where the distributional equation defines the moment functional associated with the semiclassical orthogonal polynomials. This equation is the starting point in this paper.

DEFINITION 1.1. A regular moment functional L is said to be semiclassical if and only if there exist polynomials ϕ and ψ , deg $(\psi) \ge 1$ such that

$$D(\phi L) + \psi L = 0. \tag{1}$$

Given L, among the pairs (ϕ, ψ) which satisfy (1) let s be the minimum of max $\{\deg(\phi) - 2, \deg(\psi) - 1\}$. Then L is said to be of class s. (If s = 0, the regular solutions of (1) are the functionals corresponding to the classical polynomials.)

As usual, $\langle DL, p \rangle = -\langle L, p' \rangle$ and $\langle \phi L, p \rangle = \langle L, \phi p \rangle$.

As regards the problem of the integral representation, the classical case was solved by J. L. Geronimus [4], by R. D. Morton and A. M. Krall [16], and by M. E. H. Ismail *et al.* [7]. For s > 0, examples have been given in [2, 5, 6]; the whole class of semiclassical functionals which are positive definite on the real line is given in [3]. A. P. Magnus in [9] solved the problem for "generic semiclassical" orthogonal polynomials which correspond to regular solutions of (1) in case (A) provided that the zeros of the polynomial ϕ are distinct. In [10], a solution for the problem in case (A) without restrictions on ϕ was given and the problem in case (B) was started. We summarize these results:

PROPOSITION 1.1. (a) If L is an (A)-functional and μ_n , $n \ge 0$, its moments, then there exist a positive integer N and positive constants C and M such that

$$|\mu_n| \leqslant CM^n, \qquad n \geqslant N.$$

(b) If L is an (B)-functional, there exist a positive integer N and positive constants C and M such that¹

$$|\mu_n| \leqslant CM^n n!, \qquad n \ge N.$$

From (a), the Stieltjes function associated with an (A)-functional, $S(z) = -\sum_{n=0}^{\infty} (\mu_n / z^{n+1})$, is an analytic function in |z| > M and L can be represented in the form

$$\langle L, p \rangle = \frac{1}{2\pi i} \int_{|z| = M^*} p(z) w(z) dz, \qquad M^* > M.$$

The form of S(z) is obtained from its differential equation $(\phi S)' + \psi S = D$, where D(z) is a polynomial of degree *s*. This is a characteristic of the semiclassical functionals (see [14]).

¹ From Carleman's criteria it follows that, for positive definite functionals on the real line, the problem of moments is determined.

For (B)-functionals, $\phi(x) = \sum_{k=0}^{s+1} a_k x^k$ and $\psi(x) = \sum_{k=0}^{s+1} b_k x^k$ with $b_{s+1} \neq 0$ and, since Eq. (1) is equivalent to the fact that the moments μ_n of *L* satisfy

$$-n\sum_{k=0}^{s+1}a_{k}\mu_{n+k-1} + \sum_{k=0}^{s+1}b_{k}\mu_{n+k} = 0, \qquad n = 0, 1, \dots,$$

the set of solutions is a linear space of dimension s + 1. A basis of this space will be called a Fundamental System of Solutions (FSS).

Let w(z) be a function and γ a path in the complex plane such that

$$(\phi(z) w(z))' + \psi(z) w(z) = 0, \qquad (2)$$

$$\phi(z) w(z) p(z)|_{y} = 0$$
 for every polynomial p. (3)

The moment functional L defined by

$$\langle L, p \rangle = \int_{\gamma} p(z) w(z) dz$$
 (4)

is a solution of (1) because

$$\langle D(\phi L) + \psi L, p \rangle = \int_{\gamma} (-\phi(z) w(z) p'(z) + \psi(z) w(z) p(z)) dz$$

and, by integration by parts, this is the same as

$$-\phi(z) w(z) p(z)|_{\gamma} + \int_{\gamma} \left((\phi(z) w(z))' + \psi(z) w(z) \right) p(z) dz = 0$$

from-conditions (2) and (3). This technique was described by L. M. Milne-Thomson in [15].

In [10] it has been proved that it is possible to find s + 1 independent solutions of (1), provided that $\phi = 1$ and ψ is an arbitrary polynomial of degree ≥ 1 , in the form (4) such that conditions (2) and (3) hold. Next, the same will be proved for the general case (B).

2. INTEGRAL REPRESENTATION OF (B)-FUNCTIONALS

Since the problem in case $\phi = 1$ is solved in [10], here the polynomial ϕ is always considered to have some zero. After a linear change in the variable (see [14, Proposition 6.2]) the type (B) equation may be written in such a way that one of the roots is zero and the leading coefficient of ψ is an appropriate number which simplifies calculations

$$D(\phi L) + \psi L = 0$$

$$\phi(z) = z^{r_0+1} \prod_{k=1}^{M} (z - a_k)^{r_k+1}, \quad \deg(\phi) = \sum_{k=0}^{M} (r_k + 1) = N + 1 \le s + 1.$$
(5)
$$\psi(z) = (s - N + 1) z^{s+1} + \cdots.$$

If some $r_k > 0$, we suppose that $r_0 > 0$. Of course, M may be zero. Solving the differential equation of condition (2), $(\phi w)' + \psi w = 0$, we obtain

$$w(z) = z^{\alpha_0} \sum_{k=1}^{M} (z - a_k)^{\alpha_k} \exp(-z^{s-N+1} \cdots) \times \exp\left(\frac{A_0}{z^{r_0}} + \sum_{k=1}^{M} \frac{A_k}{(z - a_k)^{r_k}}\right) \exp\left(\frac{Q(z)}{R(z)}\right),$$
(6)

where Q(z) and R(z) are polynomials with deg $Q(z) < \deg R(z)$ and such that, in the decomposition of Q(z)/R(z) in partial fractions, the exponent of each term corresponding to the zero a_k is less than r_k .

We impose the following restrictions:

• ϕ and ψ do not have any common zero. (With Proposition 3.2 in the next section, the problem in the general case is solved.)

• If some a_k is a simple zero, the corresponding exponent α_k is such that $\Re \alpha_k > -1$. (The other possibility will be considered in the next section.)

In order to simplify notation, we finally suppose that $A_k = -1$, k = 0, ..., M. An appropriate rotation around each zero a_k for the paths $\Gamma_{k,j}$, defined below, can be choosen which enables one to solve the equation when $A_k \neq -1$.

Now we define the paths such that condition (3) holds.

For each zero a_k , k = 0, ..., M, which is a multiple zero and for $j = 1, ..., r_k$, we define:

- $\beta_{k, i}$ the r_k -roots of the unity. We also consider $\arg(\beta_{k, r_k+1}) = 2\pi$.
- l_k is a positive real number whose length will be defined later.
- $\gamma_{k,j}$ is the segment from a_k in the direction $\beta_{k,j}$ and length l_k .

• $C_{k,j}$ is the arc of the circumference of radius l_k , centered on a_k , which extends from $\arg(\beta_{k,j})$ until $\arg(\beta_{k,j+1})$.

For each k, we define the length l_k to be small enough for the arcs $C_{k,j}$ of different zeros not to have any point in common.

The paths from $a_0 = 0$ to a_k , k = 1, ..., M:

• E_k is any simple curve beginning at the origin and extending in some direction d_k such that, when $z \in d_k$, $\lim_{z \to 0} \exp(-1/z^{r_0}) = 0$, arriving at a_k in direction $\beta_{k,1}$ when a_k is a multiple zero or in any direction when a_k is a simple zero, and in such a way that, avoiding points a_j , $j \neq k$, two different E_k have only the origin in common.

Finally, for m = 1, ..., s - N + 1, the paths joining zero and infinity:

• β_m are the s - N + 1-roots of the unity.

• l_0^* is a positive real number such that every path $\gamma_{k,j}$ and E_k is inside the disk centered on the origin and with radius l_0^* .

• R_0 is an arc joining 0 and l_0^* along the real line and avoiding points a_k if any of them is a positive real number.

• C_m is the arc of the circumference centered on the origin and radius l_0^* such that it goes from zero argument to the argument of β_m .

• R_m is the line in the direction of β_m corresponding to $l_0^* \leq |z| < \infty$.

Then, let

$$\begin{split} & \Gamma_m = R_0 \cup C_m \cup R_m, & m = 1, \, ..., \, s - N + 1, \\ & \Gamma_{k, \, j} = \gamma_{k, \, j} \cup C_{k, \, j} \cup (-\gamma_{k, \, j+1}), & j = 1, \, ..., \, r_k, \quad k = 0, \, ..., \, M, \end{split}$$

(see Fig. 1) and the corresponding functionals

$$\langle L_m, p \rangle = \int_{\Gamma_m} p(z) w(z) dz, \qquad m = 1, ..., s - N + 1$$

$$\langle L_{k, j}, p \rangle = \int_{\Gamma_{k, j}} p(z) w(z) dz,$$

$$j = 1, ..., r_k \text{ for each } k \text{ such that } r_k > 0,$$

$$(8)$$

$$\langle L_k^*, p \rangle = \int_{E_k} p(z) w(z) dz, \qquad k = 1, ..., M.$$
 (9)

Thus we have $s - N + 1 + r_0 + \cdots + r_M + M = s + 1$ solutions of Eq. (5).

THEOREM 2.1. $\{L_1, ..., L_{s-N+1}, L_{0,1}, ..., L_{0,r_0}, ..., L_{M,1}, ..., L_{M,r_M}, L_1^*, ..., L_M^*\}$ is an FSS of Eq. (5).

We have to prove that they are independent functionals and we begin the proof with two auxiliary results. The first one is straightforward.



FIGURE 1

LEMMA 2.1. Let $D(\phi L) + \psi L = 0$ be a type (B) equation of class s. A set of solutions $\{L_1, ..., L_{s+1}\}$ is an FSS if and only if

$$\det(\langle L_i, (x-a)^n \rangle)_{i=1, n=0}^{s+1, s} \neq 0$$

for any complex number a.

The following lemma is a kind of Theorem of Final-value for the Laplace transform (see [19, p. 249]).

LEMMA 2.2. Let $q(x) = -x^n + \sum_{k=1}^n b_k x^{n-k}$ where $b_k \in \mathscr{C}$. Let f(x) be a locally integrable bounded function in $[0, \infty)$. Let $H(\alpha)$ be the function

$$H(\alpha) = \int_0^\infty x^\alpha \exp(q(x)) \, dx, \qquad \Re(\alpha) > -1$$

and, for every fixed α , let F(t) be the function

$$F(t) = \int_0^\infty x^\alpha \exp(q(tx)) f(x) \, dx, \qquad t > 0.$$

If $\lim_{x \to \infty} f(x) = A$ then $\lim_{t \to 0^+} t^{\alpha + 1} F(t) = AH(\alpha)$.

Proof.

$$H(\alpha) = \int_0^\infty x^\alpha \exp(q(x)) \, dx = \int_0^\infty (tx)^\alpha \exp(q(tx)) t \, dx, \qquad t > 0.$$

For a given $\varepsilon > 0$, let T be such that $|f(x) - A| < \varepsilon$ for x > T. Then

$$\begin{split} |t^{\alpha+1}F(t) - AH(\alpha)| &= \left| t^{\alpha+1} \int_0^\infty x^\alpha \exp(q(tx))(f(x) - A) \, dx \right| \\ &\leq |t^{\alpha+1}| \int_0^T |x^\alpha \exp(q(tx))| \, |f(x) - A| \, dx \\ &+ \varepsilon \int_T^\infty |x^\alpha \exp(q(tx))| \, t^{\alpha+1}| \, dx \\ &\leq |t^{\alpha+1}| \, TM + \varepsilon \int_0^\infty |x^\alpha \exp(q(x))| \, dx, \end{split}$$

where *M* is an upper bound of the function $|x^{\alpha} \exp(q(tx))| |f(x) - A|$ for $x \in [0, T]$ and $t \in [0, t_0]$ for some fixed t_0 . Hence

$$\lim_{t \to 0^+} |t^{\alpha + 1} F(t) - AH(\alpha)| \leq \varepsilon \int_0^\infty |x^\alpha \exp(q(x))| dx$$

and $\lim_{t\to 0^+} t^{\alpha+1} F(t) = AH(\alpha)$ follows.

Proof of the Theorem. (I) First, we consider the particular case

$$D(xL) + ((s+1) x^{s+1} + \cdots) L = 0.$$

The only paths now are from zero to infinity, so we simplify notation

$$\langle L_j, p \rangle = \int_{\gamma_j} p(z) w(z) dz, \qquad j = 1, ..., s + 1,$$

where

$$\gamma_j \equiv \beta_j x, \quad 0 \leq x < \infty, \quad \beta_j^{s+1} = 1, \quad \text{and}$$

 $w(z) = z^{\alpha} \exp(-z^{s+1} + q(z)), \quad \deg q \leq s.$

If $\sum_{j=1}^{s+1} \lambda_j L_j = 0$ then

$$\left\langle \sum_{j=1}^{s+1} \lambda_j L_j, z^{n(s+1)+k} \right\rangle = 0; \qquad k = 0, ..., s; \quad n = 0, 1,$$
(10)

$$\langle L_j, z^{n(s+1)+k} \rangle$$

= $\int_0^\infty x^{n(s+1)+k+\alpha} \beta_j^{\alpha+k+1} \exp(-x^{s+1} + q(\beta_j x)) dx$
= $\frac{1}{s+1} \int_0^\infty \exp(-t) t^{n+(k+\alpha-s)/(s+1)} \beta_j^{\alpha+k+1} \exp(q(\beta_j t^{1/(s+1)})) dt,$

for each fixed k, (10) becomes

$$\begin{split} 0 &= \frac{1}{s+1} \int_0^\infty \exp(-t) t^{n+(k+\alpha-s)/(s+1)} \sum_{j=1}^{s+1} \lambda_j \beta_j^{\alpha+k+1} \exp(q(\beta_j t^{1/(s+1)})) \, dt \\ &= \frac{1}{s+1} \, (-1)^n \, F_k^{(n)}(1), \qquad n = 0, 1, ..., \end{split}$$

where $F_k(y)$ is the Laplace transform of

$$t^{(k+\alpha-s)/(s+1)} \sum_{j=1}^{s+1} \lambda_j \beta_j^{\alpha+k+1} \exp(q(\beta_j t^{1/(s+1)}))$$

As a consequence $F_k(y) = 0$ and

$$\sum_{j=1}^{s+1} \lambda_j \beta_j^{\alpha+k+1} \exp(q(\beta_j t^{1/(s+1)})) = 0, \qquad k = 0, ..., s$$

follows. Since det $(\beta_j^{\alpha+k+1})_{j=1,k=0}^{s+1,s} \neq 0$, we have

$$\lambda_j \exp(q(\beta_j t^{1/(s+1)})) = 0, \qquad j = 1, ..., s+1$$

from which $\lambda_j = 0, j = 1, ..., s + 1$, and $\{L_1, ..., L_{s+1}\}$ is an FSS.

(II) General case. Now we write $w(z) = z^{\alpha_0} \prod_{k=1}^{M} (z - a_k)^{\alpha_k} \times \exp(q(z)) f(z)$ and suppose

$$\sum_{m=1}^{s-N+1} \lambda_m L_m + \sum_{k=0}^{M} \sum_{j=1}^{r_k} \lambda_{k,j} L_{k,j} + \sum_{k=1}^{M} \lambda_k^* L_k^* = 0.$$
(11)

$$\sum_{m=1}^{s-N+1} \lambda_m \int_{\mathcal{R}_m} w(z) \ p(z) \ dz$$

= $-\sum_{k=0}^{M} \sum_{j=1}^{r_k} \lambda_{k,j} \int_{\Gamma_{k,j}} p(z) \ w(z) \ dz - \sum_{k=1}^{M} \lambda_k^* \int_{E_k} p(z) \ w(z) \ dz$
 $- \sum_{m=1}^{s-N+1} \lambda_m \int_{\mathcal{R}_0 \cup C_m} p(z) \ w(z) \ dz$ for every polynomial $p(z)$. (12)

Let μ be a positive integer such that $\Re(\alpha_0 + \cdots + \alpha_k + \mu) > -1$, let

$$F_{p}(t) = \sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{m}} z^{p+\alpha_{0}+\mu} \prod_{k=1}^{M} (z-a_{k})^{\alpha_{k}} \exp(q(tz)) f(z) dz$$
$$= \sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{m}} z^{p+\alpha_{0}+\dots+\alpha_{M}+\mu}$$
$$\times \prod_{k=1}^{m} \left(1 - \frac{a_{k}}{z}\right)^{\alpha_{k}} \exp(q(tz)) f(z) dz, \qquad p = 0, ..., s - N,$$

and

$$\begin{split} G_p(t) &= -\sum_{k=0}^M \sum_{j=1}^{r_k} \lambda_{k,j} \int_{\Gamma_{k,j}} z^{p+\alpha_0+\mu} \prod_{k=1}^M (z-a_k)^{\alpha_k} \exp(q(tz)) f(z) \, dz \\ &- \sum_{k=1}^M \lambda_k^* \int_{E_k} z^{p+\alpha_0+\mu} \prod_{k=1}^M (z-a_k)^{\alpha_k} \exp(q(tz)) f(z) \, dz \\ &- \sum_{m=1}^{s-N+1} \lambda_m \int_{R_0 \cup C_m} z^{p+\alpha_0+\mu} \prod_{k=1}^M (z-a_k)^{\alpha_k} \exp(q(tz)) f(z) \, dz, \\ &p = 0, ..., s-N. \end{split}$$

 $F_p(t)$ is an analytic function in $\Re(t^{s-N+1}) > 0$ and so is $G_p(t)$ in the whole complex plane. From (12), $F_p^{(n)}(1) = G_p^{(n)}(1)$, n = 0, 1, ... and $F_p(t) = G_p(t)$, $t \in \Re(t^{s-N+1}) > 0$, follows for p = 0, ..., s - N. As a consequence

$$\lim_{t \to 0^+} t^{\alpha_0 + \dots + \alpha_M + \mu + p + 1} F_p(t)$$

=
$$\lim_{t \to 0^+} t^{\alpha_0 + \dots + \alpha_M + \mu + p + 1} G_p(t) = 0, \qquad p = 0, \dots, s - N$$

Moreover,

$$F_p(t) = \sum_{m=1}^{s-N+1} \lambda_m \int_{l_0^*}^{\infty} (\beta_m x)^{p+\alpha_0+\dots+\alpha_M+\mu} \\ \times \prod_{k=1}^M \left(1 - \frac{a_k}{\beta_m x}\right)^{\alpha_k} \exp(q(t\beta_m x)) f(\beta_m x) \beta_m dx \\ = \sum_{m=1}^{s-N+1} \lambda_m \int_0^{\infty} (\beta_m x)^{p+\alpha_0+\dots+\alpha_M+\mu} \\ \times \prod_{k=1}^M \left(1 - \frac{a_k}{\beta_m x}\right)^{\alpha_k} \exp(q(t\beta_m x)) f(\beta_m x) \beta_m \chi_{[l_0^*,\infty]}(x) dx.$$

where $\chi_{[l_0^*,\infty)}(x) = 1$ when $x \in [l_0^*,\infty)$ and zero otherwise. Since $\exp(\beta_m x) = \exp(-x^{s-N+1} + \cdots)$, we can apply Lemma 2.2 to each term in the expression of $F_p(t)$ and obtain

$$0 = \lim_{t \to 0^+} t^{\alpha_0 + \dots + \alpha_M + \mu + p + 1} F_p(t)$$

= $\sum_{m=1}^{s-N+1} \lambda_m \beta_m^{\alpha_0 + \dots + \alpha_M + \mu + p + 1} \int_0^\infty x^{\alpha_0 + \dots + \alpha_M + \mu + p} \exp(q(\beta_m x)) dx$

for p = 0, ..., s - N, because $\lim_{x \to \infty} \prod_{k=1}^{M} (1 - (a_k/\beta_m x))^{\alpha_k} f(\beta_m x) = 1$, m = 1, ..., s - N + 1. This system is the same as

$$0 = \sum_{m=1}^{s-N+1} \lambda_m \int_{\delta_m} z^{\alpha_0 + \dots + \alpha_M + \mu + p} \exp(q(z)) dz, \qquad p = 0, ..., s - N,$$

where δ_m is the line $z = \beta_m x$, $0 \le x < \infty$, and its determinant may be written in the form

$$\det(\langle \overline{L}_m, z^p \rangle)_{m=1, p=0}^{s-N+1, s-N},$$

where $\{\overline{L}_1, ..., \overline{L}_{s-N+1}\}$ is an FSS for

$$D(xL) - (xq'(x) + \alpha + 1) L = 0, \qquad \alpha = \alpha_0 + \dots + \alpha_M + \mu_n$$

as was proved for the particular case of part (I). Taking into account Lemma 2.1, this determinant is non-zero and $\lambda_m = 0$, m = 1, ..., s - N + 1follows.

Equation (11) becomes

$$\sum_{k=0}^{M} \sum_{j=1}^{r_k} \lambda_{k,j} L_{k,j} + \sum_{k=1}^{M} \lambda_k^* L_k^* = 0.$$
(13)

Suppose that some a_k , and therefore a_0 (=0) is a multiple zero; otherwise there is nothing to prove with respect to $\lambda_{k,j}$. It will be proved that $\lambda_{0,j} = 0, j = 1, ..., r_0$.

From (13) it follows that

$$\left\langle \sum_{j=1}^{r_0} \lambda_{0,j} L_{0,j}, z^{nr_0 + p} \right\rangle + \left\langle \sum_{k \neq 0} \sum_{j=1}^{r_k} \lambda_{k,j} L_{k,j}, z^{nr_0 + p} \right\rangle$$
$$+ \left\langle \sum_{j=1}^{M} \lambda_k^* L_k^*, z^{nr_0 + p} \right\rangle = 0, \qquad p = 0, ..., r_0 - 1, \quad n = 0, 1,$$
(14)

Now we write $w(z) = z^{\alpha_0} \exp(-1/z^{r_0}) g(z)$. Since $\beta_{0,1}, ..., \beta_{0,r_0}$, are the r_0 -roots of the unity, we have

$$\left\langle \sum_{j=1}^{r_0} \lambda_{0,j} L_{0,j}, z^{nr_0+p} \right\rangle$$

= $\sum_{j=1}^{r_0} \lambda_{0,j} \int_{\Gamma_{0,j}} z^{nr_0+p+\alpha_0} \exp\left(\frac{-1}{z^{r_0}}\right) g(z) dz$
= $\int_{\Gamma_{0,1}} z^{nr_0+p+\alpha_0} \exp\left(\frac{-1}{t}\right) \sum_{j=1}^{r_0} \lambda_{0,j} \beta_{0,j}^{p+\alpha_0+1} g(z\beta_{0,j}) dz$

and, letting $z^{r_0} = t$, the above equation reduces to

$$\frac{1}{r_0} \int_{\Gamma} t^n \exp\left(\frac{-1}{t}\right) t^{(p+\alpha_0+1-r_0)/r_0} \sum_{j=1}^{r_0} \lambda_{0,j} \beta_{0,j}^{\alpha_0+p+1} g(t^{1/r_0} \beta_{0,j}) dt,$$

where Γ is the path in Fig. 2. On the other hand, after making the substitution $z^{r_0} = t$, we also have

$$\left\langle \sum_{k \neq 0} \sum_{j=1}^{r_k} \lambda_{k,j} L_{k,j}, z^{nr_0 + p} \right\rangle$$

= $\frac{1}{r_0} \sum_{k \neq 0} \sum_{j=1}^{r_k} \lambda_{k,j} \int_{\overline{\Gamma}_{k,j}} t^n \exp\left(\frac{-1}{t}\right) t^{(p + \alpha_0 - r_0 + 1)/r_0} g(t^{1/r_0}) dt,$
 $p = 0, ..., r_0 - 1, \quad n = 0, 1, ...,$

where $\overline{\Gamma}_{k, i}$ is a curve in the region $|t| > l_0^{r_0}$. Furthermore

$$\left\langle \sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}, z^{nr_{0}+p} \right\rangle$$

$$= \frac{1}{r_{0}} \sum_{k=1}^{M} \lambda_{k}^{*} \int_{\overline{E}_{k}} t^{n} \exp\left(\frac{-1}{t}\right) t^{(p+\alpha_{0}-r_{0}+1)/r_{0}} g(t^{1/r_{0}}) dt,$$

$$p = 0, ..., r_{0} - 1, \quad n = 0, 1, ...,$$



FIGURE 2

where \overline{E}_k is a curve such that its part near zero is in the region $\Re(t) > 0$, and the corresponding integral converges.

Hence, from (14) it follows that

$$\begin{split} \int_{\Gamma} \frac{1}{t-\zeta} \exp\left(\frac{-1}{t}\right) t^{(p+\alpha-r_0+1)/r_0} \sum_{j=1}^{r_0} \lambda_{0,j} \beta_{0,j}^{\alpha_0+p+1} g(t^{1/r_0} \beta_{0,j}) dt \\ &+ \sum_{k\neq 0} \sum_{j=1}^{r_k} \lambda_{k,j} \int_{\overline{\Gamma}_{k,j}} \frac{1}{t-\zeta} \exp\left(\frac{-1}{t}\right) t^{(p+\alpha_0-r_0+1)/r_0} g(t^{1/r_0}) dt \\ &+ \sum_{k=1}^{M} \lambda_k^* \int_{\overline{E}_k} \frac{1}{t-\zeta} \exp\left(\frac{-1}{t}\right) t^{(p+\alpha_0-r_0+1)/r_0} g(t^{1/r_0}) dt = 0 \end{split}$$

for ζ such that $|\zeta|$ is large enough and for each $p = 0, ..., r_0 - 1$. With p fixed and denoting each term in the last expression in $H_1(\zeta)$, $H_2(\zeta)$, and $H_3(\zeta)$, it becomes

$$H_1(\zeta) + H_2(\zeta) + H_3(\zeta) = 0$$
 for $|\zeta|$ sufficiently large.

For $\varepsilon > 0$, if we use $H_{1,\varepsilon}(\zeta)$ to refer to the integral of the function which defines $H_1(\zeta)$ but now over the path Γ_{ε} of Fig. 3, we have $H_1(\zeta) = H_{1,\varepsilon}(\zeta)$ when $|\zeta| > l_0^{r_0}$, whence

$$H_{1,e}(\zeta) + H_2(\zeta) + H_3(\zeta) = 0$$

for $|\zeta| > \varepsilon$ and ζ outside the curves $\overline{\Gamma}_{k, i}$ and \overline{E}_{k} .

Let C be the curve in Fig. 4 and let ζ be a point such that $\varepsilon < |\zeta| < l_0^{r_0}$ and $\zeta \notin (\varepsilon, l_0^{r_0})$. By Cauchy's theorem we have



FIGURE 3



FIGURE 4

$$2\pi i \exp\left(\frac{-1}{\zeta}\right) \zeta^{(p+\alpha_0-r_0+1)/r_0} \sum_{j=1}^{r_0} \lambda_{0,j} \beta_{0,j}^{\alpha_0+p+1} g(\zeta^{1/r_0} \beta_{0,j})$$

= $\int_C \frac{1}{t-\zeta} \exp\left(\frac{-1}{t}\right) t^{(p+\alpha_0-r_0+1)/r_0} \sum_{j=1}^{r_0} \lambda_{0,j} \beta_{0,j}^{\alpha_0+p+1} g(t^{1/r_0} \beta_{0,j}) dt$
= $H_1(\zeta) - H_{1,\varepsilon}(\zeta) = H_1(\zeta) + H_2(\zeta) + H_3(\zeta).$ (15)

Let ζ be a point in $(-\frac{1}{2}, 0)$. Then $|t - \zeta| \ge t$ when $t \in [0, l_0^{r_0}]$, and $|t - \zeta| \ge \frac{1}{2}$ when t lies in $|t| = l_0^{r_0}$. Therefore $H_1(\zeta)$ is a bounded function when $\zeta \in (-\frac{1}{2}, 0)$. Moreover, $H_2(\zeta)$ and $H_3(\zeta)$ are bounded too in the same region. As a consequence, equality (15) only holds when

$$\sum_{j=1}^{r_0} \lambda_{0, j} \beta_{0, j}^{\alpha_0 + p + 1} g(\zeta^{1/r_0} \beta_{0, j}) = 0, \qquad p = 0, ..., r_0 - 1$$

from which $\lambda_{0, j} = 0, j = 1, ..., r_0$.

It is clear that the preceding work can be carried over to any multiple zero a_k by a change $z - a_k = t$. Hence $\lambda_{k,j} = 0, j = 1, ..., r_k$, for every k such that a_k is a multiple zero. It remains to be proved that $\lambda_k^* = 0$ for k = 1, ..., M.

$$\left\langle \sum_{k=1}^{M} \lambda_k^* L_k^*, p \right\rangle = \sum_{k=1}^{M} \lambda_k^* \int_{E_k} w(z) \ p(z) \ dz = \int_X w(z) \sum_{k=1}^{M} \lambda_k^* \chi_{E_k}(z) \ p(z) \ dz,$$

where $X = \bigcup_{k=1}^{M} E_k$, and $\chi_{E_k}(z) = 1$ when $z \in E_k$ and zero otherwise. It is clear that this is a bounded functional over the space of continuous functions on X and, since the complement of X is connected and its interior is empty, by Merguelian's theorem, there exists only one extension of the functional over the continuous functions on X. Then, if

$$\left\langle \sum_{k=1}^{M} \lambda_k^* L_k^*, p \right\rangle = 0,$$
 for every polynomial p ,

it is zero on the continuous functions. Hence, from Riesz Representation Theorem, this functional may be represented in a unique form and it follows that

$$w(z)\sum_{k=1}^{M}\lambda_k^*\chi_{E_k}(z)=0$$

for every z where this is a continuous function. Then $\lambda_k^* = 0$ for k = 1, ..., M.

3. REGULARIZATION

When $\Re(\alpha_k) \leq -1$ for some simple zero a_k , the corresponding integrals are not convergent and a regularization is needed. It will be done recurrently over the integer part of $\Re(\alpha_k)$.

Given the equation $D(\phi L) + \psi L = 0$, if a is a zero of ϕ we denote

$$\phi(x) = (x - a) \phi_a(x), \qquad \psi(x) = (x - a) \psi_a(x) + \psi(a),$$

and, using Maroni's techniques, we consider

$$\langle (x-a)^{-1} L, p \rangle = \left\langle L, \frac{p(x) - p(a)}{x-a} \right\rangle.$$

PROPOSITION 3.1. Let a be one zero of ϕ such that $\psi(a) \neq 0$. If $\{L_1, ..., L_{s+1}\}$ is an FSS of the equation of class s and type (B)

$$D(\phi L) + (\psi - \phi_a) L = 0,$$

then

$$\{(x-a)^{-1} L_1 + M_1 \delta(x-a), ..., (x-a)^{-1} L_{s+1} + M_{s+1} \delta(x-a)\},\$$

where $M_j = -\langle L_j, \psi_a \rangle / \psi(a)$, is an FSS of $D(\phi L) + \psi L = 0$.

Proof. Let $L_j^* = (x-a)^{-1} L_j + M_j \delta(x-a)$, then $L_j = (x-a) L_j^*$. Furthermore

$$D((x-a)^2 \phi_a L_j^*) = D((x-a) \phi_a L_j) = -(\psi - \phi_a) L_j$$

and thus

$$D((x-a)^2 \phi_a L_j^*) + (x-a)(\psi - \phi_a) L_j^* = 0.$$

Taking the derivative, we obtain $(x - a)(D(\phi L_j^*) + \psi L_j^*) = 0$, which means that

$$D(\phi L_j^*) + \psi L_j^* = \langle L_j^*, \psi \rangle \,\delta(x-a).$$

Moreover

$$\begin{split} \langle L_j^*, \psi \rangle &= \left\langle L_j, \frac{\psi(x) - \psi(a)}{x - a} \right\rangle + M_j \langle \delta(x - a), \psi \rangle \\ &= \langle L_j, \psi_a \rangle + M_j \psi(a) = 0 \end{split}$$

from the definition of M_j , and it follows that $D(\phi L_j^*) + \psi L_j^* = 0$. On the other hand

$$\begin{array}{cccc} \langle L_{1}^{*}, 1 \rangle, & \cdot & , \langle L_{s+1}^{*}, 1 \rangle \\ \langle L_{1}^{*}, x-a \rangle, & \cdot & , \langle L_{s+1}^{*}, x-a \rangle \\ \vdots & \vdots & \vdots \\ \langle L_{1}^{*}, (x-a)^{s} \rangle, & \cdot & , \langle L_{s+1}^{*}, (x-a)^{s} \rangle \end{array} \\ = \left| \begin{array}{c} M_{1}, & \cdot & , M_{s+1} \\ \langle L_{1}, 1 \rangle, & \cdot & , \langle L_{s+1}, 1 \rangle \\ \vdots & \vdots & \vdots \\ \langle L_{1}, (x-a)^{s-1} \rangle, & \cdot & , \langle L_{s+1}, (x-a)^{s-1} \rangle \end{array} \right| \\ = -\frac{K}{\psi(a)} \left| \begin{array}{c} \langle L_{1}, (x-a)^{s} \rangle, & \cdot & , \langle L_{s+1}, (x-a)^{s} \rangle \\ \vdots & \vdots & \vdots \\ \langle L_{1}, (x-a)^{s-1} \rangle, & \cdot & , \langle L_{s+1}, (x-a)^{s} \rangle \\ \vdots & \vdots & \vdots \\ \langle L_{1}, (x-a)^{s-1} \rangle, & \cdot & , \langle L_{s+1}, (x-a)^{s-1} \rangle \end{array} \right|,$$

where K is the coefficient of degree s + 1 of ψ which is non-zero because the equation is of type (B). The last identity holds because the remaining terms in the first row are a linear combination of the others. By hypothesis $\{L_1, ..., L_{s+1}\}$ is an FSS and, from Lemma 2.1, the last determinant is non-zero. This means that $\{L_1^*, ..., L_{s+1}^*\}$ is an FSS of $D(\phi L) + \psi L = 0$. Let us now explain the recursive process.

Suppose initially that only one α_k corresponding to a simple zero a_k has $\Re(\alpha_k) \leq -1$ and that $\alpha_k \neq -1, -2, \dots$. If $-2 < \Re(\alpha_k) \leq -1$, equation $D(\phi L) + (\psi - \phi_{a_k}) L = 0$ is covered by Theorem 2.1 because

$$\frac{w'(z)}{w(z)} = -\frac{\psi(z) - \phi_{a_k}(z) + \phi'(z)}{\phi(z)} = -\frac{\psi(z) + \phi'(z)}{\phi(z)} + \frac{1}{z - a_k}.$$

By applying Proposition 3.1 we obtain the solution for $D(\phi L) + \psi L = 0$. In order to apply Proposition 3.1 we need $\psi(a_k) \neq 0$, but this is equivalent to the condition $\alpha_k \neq -1$ because a_k is a simple zero. By repeating the above process as many times as required by the integer part of $\Re(\alpha_k)$, we have the solution for case $\Re(\alpha_k) \leq -1$ provided that $\alpha_k \neq -1, -2, ...$

Let us now solve case $\alpha_k = -1$, the solution of which can be extended with Proposition 3.1 to obtain the solution for $\alpha_k = -2, -3, ...$

PROPOSITION 3.2. Given the equation $D(\phi L) + \psi L = 0$, suppose that, for some zero a of ϕ , $\psi(a) = 0$. Let $\{L_1, ..., L_s\}$ be an FSS of the equation of class s - 1, $D(\phi_a L) + \psi_a L = 0$. Then

$$\{\delta(x-a), (x-a)^{-1}L_1, ..., (x-a)^{-1}L_s\}$$

is an FSS of $D(\phi L) + \psi L = 0$.

Proof. It is straightforward to show that $\delta(x-a)$ is a solution. Let $L_i^* = (x-a)^{-1} L_i$. Then $L_i = (x-a) L_i^*$, and it follows that

$$D((x-a)\phi_a L_j^*) = D(\phi_a L_j) = -\psi_a L_j = -(x-a)\psi_a L_j^* = -\psi L_j^*.$$

Moreover

$$\left| \begin{array}{ccc} \langle \delta(x-a), 1 \rangle, & \cdot & \langle \delta(x-a), (x-a)^s \rangle \\ \langle L_1^*, 1 \rangle, & \cdot & \langle L_1^*, (x-a)^s \rangle \\ \vdots & \vdots & \vdots \\ \langle L_s^*, 1 \rangle, & \cdot & \langle L_s^*, (x-a)^s \rangle \end{array} \right|$$

$$= \left| \begin{array}{ccc} 1 & 0 & \cdot & 0 \\ 0 & \langle L_1, 1 \rangle & \cdot & \langle L_1, (x-a)^{s-1} \rangle \\ \vdots & \vdots & \vdots \\ 0 & \langle L_s, 1 \rangle & \cdot & \langle L_s, (x-a)^{s-1} \rangle \end{array} \right|$$

which is non-zero because $\{L_1, ..., L_s\}$ is an FSS. Hence $\{\delta(x-a), (x-a)^{-1}L_1, ..., (x-a)^{-1}L_s\}$ is an FSS of $D(\phi L) + \psi L = 0$.

The equation $D(\phi_a L) + \psi_a L = 0$, when regularization is necessary for only one zero, gives rise to two possibilities:

- (1) The solution of the equation is covered by Theorem 2.1
- (2) The equation reduces to DL + KL = 0 where $K \neq 0$ is a constant.

The equation in case (2) yields

$$\begin{cases} K \langle L, 1 \rangle = 0 \\ -n \langle L, x^{n-1} \rangle + K \langle L, x^n \rangle = 0, \quad n \ge 1, \end{cases}$$

and $\langle L, x^n \rangle = 0, n \ge 0$, so L = 0.

Thus, the equation is solved when only one zero has its real part less than or equal to -1. If there were more than one zero with the real part less than or equal to -1, Propositions 3.1 and 3.2 could be used to reduce this case to the previous case.

EXAMPLE. We present an example of the regularization method for a semiclassical functional of class s = N - 1 which covers Laguerre functionals (N = 1), studied by Morton and Krall in [16], and an example of Airy (N = 3) and Freud functionals (N = 4). Examples of Airy functionals may be seen in [12] and for Freud ones see, for example, [1].

Let L be such that

$$D(xL) + (Nx^N - \alpha - 1) L = 0$$

One of the solutions is, for $\Re \alpha > -1$,

$$\langle L^{(\alpha)}, p \rangle = \int_0^\infty x^\alpha e^{-x^N} p(x) \, dx.$$

Let us consider a real number ε such that $-1 < \varepsilon < 0$. Our aim is to obtain the solution for $\alpha = \varepsilon - 1, \varepsilon - 2, ..., \varepsilon - n, ...$ From Proposition 3.1, the corresponding solution of

$$D(xL) + (Nx^N - (\varepsilon - n) - 1) L = 0$$

can be written as

$$L^{(\varepsilon-n)} = x^{-1}L^{(\varepsilon-n+1)} + M_n \,\delta,$$

where

$$M_n = \frac{\langle L^{(\varepsilon - n + 1)}, Nx^{N - 1} \rangle}{\varepsilon + 1 - n}.$$

With the same notation and using induction we get

$$L^{(\varepsilon-n)} = x^{-n} L^{(\varepsilon)} + \sum_{k=1}^{n} \frac{(-1)^{n-k}}{(n-k)!} M_k \,\delta^{(n-k)},\tag{16}$$

where

$$\langle x^{-n}L^{(e)}, p \rangle = \left\langle L^{(e)}, \frac{1}{x^n} \left(p(x) - \sum_{j=0}^{n-1} \frac{p^{(j)}(0)}{j!} x^j \right) \right\rangle$$
$$= \int_0^\infty x^{e-n} e^{-x^N} \left\{ p(x) - \sum_{j=0}^{n-1} \frac{p^{(j)}(0)}{j!} x^j \right\} dx$$

and the derivatives of δ appear in (6) because $x^{-k}\delta = ((-1)^k/k!)\delta^{(k)}$. So, we have to obtain M_k , k = 1, ..., n.

Setting k = vN + j, j = 1, ..., N, v = 1, 2, ..., we have

$$\begin{split} M_{\nu N+j} &= \frac{\langle L^{(\varepsilon-\nu N-j+1)}, Nx^{N-1} \rangle}{\varepsilon+1 - (\nu N+j)} \\ &= \frac{N}{\varepsilon+1 - (\nu N+j)} \langle x^{-1} L^{(\varepsilon-\nu N-j+2)} + M_{\nu N+j} \, \delta, x^{N-1} \rangle \\ &= \frac{N}{\varepsilon+1 - (\nu N+j)} \langle L^{(\varepsilon-\nu N-j+N)}, 1 \rangle \\ &= \frac{N}{\varepsilon+1 - (\nu N+j)} \langle x^{-1} L^{(\varepsilon-(\nu-1)N-j+1)} + M_{(\nu-1)N+j} \, \delta, 1 \rangle \\ &= \frac{N}{\varepsilon+1 - (\nu N+j)} \, M_{(\nu-1)N+j}. \end{split}$$

As a consequence, for j = 1, ..., N and v = 0, 1, ..., we have

$$M_{\nu N+j} = \frac{N}{\varepsilon + 1 - (\nu N+j)} \frac{N}{\varepsilon + 1 - ((\nu - 1)N+j)} \cdots \frac{N}{\varepsilon + 1 - j} \langle L^{(\varepsilon)}, x^{N-j} \rangle$$
(17)

because

$$M_{j} = \frac{N}{\varepsilon + 1 - j} \langle L^{(\varepsilon)}, x^{N-j} \rangle, \qquad j = 1, ..., N.$$

Hence, letting $M_{\nu N+j} = A_{\nu N+j} \langle L^{(\varepsilon)}, x^{N-j} \rangle$, and n = kN + r, r = 1, ..., N, expression (17) in (16) yields

$$\langle L^{(\varepsilon-kN-r)}, p \rangle$$

= $\langle x^{-(kN+r)}L^{(\varepsilon)}, p \rangle + \sum_{\nu=0}^{k-1} \sum_{j=1}^{N} \frac{A_{\nu N+j}p^{(k-\nu)N+r-j}(0)}{((k-\nu)N+r-j)!} \langle L^{(\varepsilon)}, x^{N-j} \rangle$
+ $\sum_{j=1}^{r} \frac{A_{kN+j}p^{(r-j)}(0)}{(r-j)!} \langle L^{(\varepsilon)}, x^{N-j} \rangle.$

Then

$$\langle L^{(\varepsilon-kN-r)}, p \rangle = \int_0^\infty x^{\varepsilon-kN-r} e^{-x^N} \left\{ p(x) - \sum_{j=0}^{kN+r-1} \frac{p^{(j)}(0)}{j!} x^j + \sum_{\nu=0}^{k-1} \sum_{j=1}^N \frac{A_{\nu N+j} p^{(k-\nu)N+r-j}(0)}{((k-\nu)N+r-j)!} x^{(k+1)N+r-j} + \sum_{j=1}^r \frac{A_{kN+j} p^{(r-j)}(0)}{(r-j)!} x^{(k+1)N+r-j} \right\} dx$$

and the $A_{\nu N+j}$ are defined by the recurrent relation

$$A_{j} = \frac{N}{\varepsilon + 1 - j}, \qquad j = 1, ..., N$$
$$A_{\nu N + j} = \frac{N}{\varepsilon + 1 - (\nu N + j)} A_{(\nu - 1)N + j}, \qquad j = 1, ..., N; \ \nu = 1, 2, ... \blacksquare$$

In cases $\alpha = -1, -2, ...,$ the solutions have a different form. For $\alpha = -1, D(xL) + Nx^{N}L = 0$, by Proposition 3.2 one must solve

$$DL + Nx^{N-1}L = 0.$$

Any solution of this equation has the form

$$\langle L, p \rangle = \sum_{i=1}^{N-1} \lambda_i \int_{\gamma_i} p(z) e^{-z^N} dz,$$

where the γ_i are defined in Theorem 2.1. Therefore, by Proposition 3.2, any solution $L_N^{(-1)}$ of $D(xL) + Nx^NL = 0$ may be written as

$$\langle L_N^{(-1)}, p \rangle = \sum_{i=1}^{N-1} \lambda_i \int_{\gamma_i} \frac{p(z) - p(0)}{z} e^{-z^N} dz + \lambda_N p(0)$$

and the corresponding solutions for $\alpha = -2, -3, ...$ must be obtained with Proposition 3.1 again. Letting

$$\langle L_{N,i}^{(-1)}, p \rangle = \int_{\gamma_i} \frac{p(z) - p(0)}{z} e^{-z^N} dz, \qquad i = 1, \dots, N-1,$$

$$\langle L_{N,N}^{(-1)}, p \rangle = \langle \delta, p \rangle,$$

in the same way as before, for i = 1, ..., N we have

$$\langle L_{N,i}^{(-1-kN-r)}, p \rangle = \langle x^{-(kN+r)} L_{N,i}^{(-1)}, p \rangle$$

$$+ \sum_{\nu=0}^{k-1} \sum_{j=1}^{N} \frac{A_{\nu N+j} p^{(k-\nu)N+r-j}(0)}{((k-\nu)N+r-j)!} \langle L_{N,i}^{(-1)}, x^{N-j} \rangle$$

$$+ \sum_{j=1}^{r} \frac{A_{kN+j} p^{(r-j)}(0)}{(r-j)!} \langle L_{N,i}^{(-1)}, x^{N-j} \rangle,$$

where

$$A_{j} = -\frac{N}{j}, \qquad j = 1, ..., N$$

$$A_{\nu N+j} = -\frac{N}{\nu N+j} A_{(\nu-1)N+j}, \qquad j = 1, ..., N; \ \nu = 1, 2,$$

Remark. Freud weights are explicitly related to this problem. In fact, the associated linear functional is a B-functional. The distributional equation allows us to obtain the nonlinear equations (the so-called Freud equations) of the coefficients of the three-term recurrence relation of the corresponding sequence of orthogonal polynomials. Furthermore, the solutions of such equations are given in terms of Hankel determinants whose entries are the moments (μ_k) . They satisfy a linear recurrence relation as we pointed out in the Introduction. In a private communication, A. P. Magnus announced the connection between Freud equations and discrete Painlevé equations when $\phi = 1$ and ψ is an odd polynomial.

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