# Complex Path Integral Representation for Semiclassical Linear Functionals 

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Semiclassical linear functionals are characterized by the distributional equation $D(\phi L)+\psi L=0$ where $\phi$ and $\psi$ are arbitrary polynomials with the condition $\operatorname{deg}(\psi) \geqslant 1$. Two cases are considered:
(A) $\operatorname{deg}(\phi)>\operatorname{deg}(\psi)$
(B) $\operatorname{deg}(\phi) \leqslant \operatorname{deg}(\psi)$.

In an earlier work by the authors (J. Comput. Appl. Math. 57 (1995), 239-249) integral representations are given for semiclassical functionals in case (A). Here the problem is continued and case ( B ) is solved: it is always possible to choose some path $\gamma$ in the complex plane such that every solution, regular or not, of $D(\phi L)+\psi L=0$ can be represented in the form $\langle L, p\rangle=\int_{\gamma} w(z) p(z) d z$ where $w(z)$ is a solution of the differential equation $(\phi w)^{\prime}+\psi w=0$. In some cases, the expression for $L$ is a singular integral and a regularization process is given. © 1998 Academic Press

## 1. INTRODUCTION

The first authors to study semiclassical orthogonal polynomials were E. N. Laguerre [8] and J. Shohat [18]. Recently, a unified theory of these polynomials has been developed by P. Maroni in [11, 13, 14], where the distributional equation defines the moment functional associated with the semiclassical orthogonal polynomials. This equation is the starting point in this paper.

Definition 1.1. A regular moment functional $L$ is said to be semiclassical if and only if there exist polynomials $\phi$ and $\psi, \operatorname{deg}(\psi) \geqslant 1$ such that

$$
\begin{equation*}
D(\phi L)+\psi L=0 . \tag{1}
\end{equation*}
$$

Given $L$, among the pairs $(\phi, \psi)$ which satisfy (1) let $s$ be the minimum of $\max \{\operatorname{deg}(\phi)-2, \operatorname{deg}(\psi)-1\}$. Then $L$ is said to be of class $s$. (If $s=0$, the regular solutions of (1) are the functionals corresponding to the classical polynomials.)

As usual, $\langle D L, p\rangle=-\left\langle L, p^{\prime}\right\rangle$ and $\langle\phi L, p\rangle=\langle L, \phi p\rangle$.
As regards the problem of the integral representation, the classical case was solved by J. L. Geronimus [4], by R. D. Morton and A. M. Krall [16], and by M. E. H. Ismail et al. [7]. For $s>0$, examples have been given in $[2,5,6]$; the whole class of semiclassical functionals which are positive definite on the real line is given in [3]. A. P. Magnus in [9] solved the problem for "generic semiclassical" orthogonal polynomials which correspond to regular solutions of (1) in case (A) provided that the zeros of the polynomial $\phi$ are distinct. In [10], a solution for the problem in case (A) without restrictions on $\phi$ was given and the problem in case (B) was started. We summarize these results:

Proposition 1.1. (a) If $L$ is an (A)-functional and $\mu_{n}, n \geqslant 0$, its moments, then there exist a positive integer $N$ and positive constants $C$ and $M$ such that

$$
\left|\mu_{n}\right| \leqslant C M^{n}, \quad n \geqslant N .
$$

(b) If $L$ is an (B)-functional, there exist a positive integer $N$ and positive constants $C$ and $M$ such that ${ }^{1}$

$$
\left|\mu_{n}\right| \leqslant C M^{n} n!, \quad n \geqslant N .
$$

From (a), the Stieltjes function associated with an (A)-functional, $S(z)=-\sum_{n=0}^{\infty}\left(\mu_{n} / z^{n+1}\right)$, is an analytic function in $|z|>M$ and $L$ can be represented in the form

$$
\langle L, p\rangle=\frac{1}{2 \pi i} \int_{|z|=M^{*}} p(z) w(z) d z, \quad M^{*}>M .
$$

The form of $S(z)$ is obtained from its differential equation $(\phi S)^{\prime}+\psi S=D$, where $D(z)$ is a polynomial of degree $s$. This is a characteristic of the semiclassical functionals (see [14]).

[^0]For (B)-functionals, $\phi(x)=\sum_{k=0}^{s+1} a_{k} x^{k}$ and $\psi(x)=\sum_{k=0}^{s+1} b_{k} x^{k}$ with $b_{s+1} \neq 0$ and, since Eq. (1) is equivalent to the fact that the moments $\mu_{n}$ of $L$ satisfy

$$
-n \sum_{k=0}^{s+1} a_{k} \mu_{n+k-1}+\sum_{k=0}^{s+1} b_{k} \mu_{n+k}=0, \quad n=0,1, \ldots,
$$

the set of solutions is a linear space of dimension $s+1$. A basis of this space will be called a Fundamental System of Solutions (FSS).

Let $w(z)$ be a function and $\gamma$ a path in the complex plane such that

$$
\begin{gather*}
(\phi(z) w(z))^{\prime}+\psi(z) w(z)=0  \tag{2}\\
\left.\phi(z) w(z) p(z)\right|_{\gamma}=0 \quad \text { for every polynomial } p . \tag{3}
\end{gather*}
$$

The moment functional $L$ defined by

$$
\begin{equation*}
\langle L, p\rangle=\int_{\gamma} p(z) w(z) d z \tag{4}
\end{equation*}
$$

is a solution of (1) because

$$
\langle D(\phi L)+\psi L, p\rangle=\int_{\gamma}\left(-\phi(z) w(z) p^{\prime}(z)+\psi(z) w(z) p(z)\right) d z
$$

and, by integration by parts, this is the same as

$$
-\left.\phi(z) w(z) p(z)\right|_{\gamma}+\int_{\gamma}\left((\phi(z) w(z))^{\prime}+\psi(z) w(z)\right) p(z) d z=0
$$

from-conditions (2) and (3). This technique was described by L. M. MilneThomson in [15].

In [10] it has been proved that it is possible to find $s+1$ independent solutions of (1), provided that $\phi=1$ and $\psi$ is an arbitrary polynomial of degree $\geqslant 1$, in the form (4) such that conditions (2) and (3) hold. Next, the same will be proved for the general case (B).

## 2. INTEGRAL REPRESENTATION OF (B)-FUNCTIONALS

Since the problem in case $\phi=1$ is solved in [10], here the polynomial $\phi$ is always considered to have some zero. After a linear change in the variable (see [14, Proposition 6.2]) the type (B) equation may be written in such a way that one of the roots is zero and the leading coefficient of $\psi$ is an appropriate number which simplifies calculations

$$
\begin{gather*}
D(\phi L)+\psi L=0 \\
\phi(z)=z^{r_{0}+1} \prod_{k=1}^{M}\left(z-a_{k}\right)^{r_{k}+1}, \quad \operatorname{deg}(\phi)=\sum_{k=0}^{M}\left(r_{k}+1\right)=N+1 \leqslant s+1 .  \tag{5}\\
\psi(z)=(s-N+1) z^{s+1}+\cdots .
\end{gather*}
$$

If some $r_{k}>0$, we suppose that $r_{0}>0$. Of course, $M$ may be zero. Solving the differential equation of condition (2), ( $\phi w)^{\prime}+\psi w=0$, we obtain

$$
\begin{align*}
w(z)= & z^{\alpha_{0}} \sum_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \exp \left(-z^{s-N+1} \ldots\right) \\
& \times \exp \left(\frac{A_{0}}{z^{r_{0}}}+\sum_{k=1}^{M} \frac{A_{k}}{\left(z-a_{k}\right)^{r_{k}}}\right) \exp \left(\frac{Q(z)}{R(z)}\right), \tag{6}
\end{align*}
$$

where $Q(z)$ and $R(z)$ are polynomials with $\operatorname{deg} Q(z)<\operatorname{deg} R(z)$ and such that, in the decomposition of $Q(z) / R(z)$ in partial fractions, the exponent of each term corresponding to the zero $a_{k}$ is less than $r_{k}$.

We impose the following restrictions:

- $\phi$ and $\psi$ do not have any common zero. (With Proposition 3.2 in the next section, the problem in the general case is solved.)
- If some $a_{k}$ is a simple zero, the corresponding exponent $\alpha_{k}$ is such that $\mathfrak{R} \alpha_{k}>-1$. (The other possibility will be considered in the next section.)

In order to simplify notation, we finally suppose that $A_{k}=-1, k=0, \ldots, M$. An appropriate rotation around each zero $a_{k}$ for the paths $\Gamma_{k, j}$, defined below, can be choosen which enables one to solve the equation when $A_{k} \neq-1$.

Now we define the paths such that condition (3) holds.
For each zero $a_{k}, k=0, \ldots, M$, which is a multiple zero and for $j=1, \ldots, r_{k}$, we define:

- $\beta_{k, j}$ the $r_{k}$-roots of the unity. We also consider $\arg \left(\beta_{k, r_{k}+1}\right)=2 \pi$.
- $l_{k}$ is a positive real number whose length will be defined later.
- $\gamma_{k, j}$ is the segment from $a_{k}$ in the direction $\beta_{k, j}$ and length $l_{k}$.
- $C_{k, j}$ is the arc of the circumference of radius $l_{k}$, centered on $a_{k}$, which extends from $\arg \left(\beta_{k, j}\right)$ until $\arg \left(\beta_{k, j+1}\right)$.

For each $k$, we define the length $l_{k}$ to be small enough for the $\operatorname{arcs} C_{k, j}$ of different zeros not to have any point in common.

The paths from $a_{0}=0$ to $a_{k}, k=1, \ldots, M$ :

- $E_{k}$ is any simple curve beginning at the origin and extending in some direction $d_{k}$ such that, when $z \in d_{k}, \lim _{z \rightarrow 0} \exp \left(-1 / z^{r_{0}}\right)=0$, arriving at $a_{k}$ in direction $\beta_{k, 1}$ when $a_{k}$ is a multiple zero or in any direction when $a_{k}$ is a simple zero, and in such a way that, avoiding points $a_{j}, j \neq k$, two different $E_{k}$ have only the origin in common.

Finally, for $m=1, \ldots, s-N+1$, the paths joining zero and infinity:

- $\beta_{m}$ are the $s-N+1$-roots of the unity.
- $l_{0}^{*}$ is a positive real number such that every path $\gamma_{k, j}$ and $E_{k}$ is inside the disk centered on the origin and with radius $l_{0}^{*}$.
- $R_{0}$ is an arc joining 0 and $l_{0}^{*}$ along the real line and avoiding points $a_{k}$ if any of them is a positive real number.
- $C_{m}$ is the arc of the circumference centered on the origin and radius $l_{0}^{*}$ such that it goes from zero argument to the argument of $\beta_{m}$.
- $R_{m}$ is the line in the direction of $\beta_{m}$ corresponding to $l_{0}^{*} \leqslant|z|<\infty$.

Then, let

$$
\begin{array}{rlrl}
\Gamma_{m} & =R_{0} \cup C_{m} \cup R_{m}, & m=1, \ldots, s-N+1, \\
\Gamma_{k, j} & =\gamma_{k, j} \cup C_{k, j} \cup\left(-\gamma_{k, j+1}\right), & & j=1, \ldots, r_{k}, \quad k=0, \ldots, M,
\end{array}
$$

(see Fig. 1) and the corresponding functionals

$$
\begin{align*}
&\left\langle L_{m}, p\right\rangle= \int_{\Gamma_{m}} p(z) w(z) d z, \quad m=1, \ldots, s-N+1  \tag{7}\\
&\left\langle L_{k, j}, p\right\rangle=\int_{\Gamma_{k, j}} p(z) w(z) d z, \\
& j=1, \ldots, r_{k} \text { for each } k \text { such that } r_{k}>0,  \tag{8}\\
&\left\langle L_{k}^{*}, p\right\rangle= \int_{E_{k}} p(z) w(z) d z, \quad k=1, \ldots, M . \tag{9}
\end{align*}
$$

Thus we have $s-N+1+r_{0}+\cdots+r_{M}+M=s+1$ solutions of Eq. (5).
Theorem 2.1. $\left\{L_{1}, \ldots, L_{s-N+1}, L_{0,1}, \ldots, L_{0, r_{0}}, \ldots, L_{M, 1}, \ldots, L_{M, r_{M}}\right.$, $\left.L_{1}^{*}, \ldots, L_{M}^{*}\right\}$ is an FSS of Eq. (5).

We have to prove that they are independent functionals and we begin the proof with two auxiliary results. The first one is straightforward.


FIGURE 1

Lemma 2.1. Let $D(\phi L)+\psi L=0$ be a type (B) equation of class s. A set of solutions $\left\{L_{1}, \ldots, L_{s+1}\right\}$ is an FSS if and only if

$$
\operatorname{det}\left(\left\langle L_{i},(x-a)^{n}\right\rangle\right)_{i=1, n=0}^{s+1, s} \neq 0
$$

for any complex number $a$.
The following lemma is a kind of Theorem of Final-value for the Laplace transform (see [19, p. 249]).

Lemma 2.2. Let $q(x)=-x^{n}+\sum_{k=1}^{n} b_{k} x^{n-k}$ where $b_{k} \in \mathscr{C}$. Let $f(x)$ be a locally integrable bounded function in $[0, \infty)$. Let $H(\alpha)$ be the function

$$
H(\alpha)=\int_{0}^{\infty} x^{\alpha} \exp (q(x)) d x, \quad \mathfrak{R}(\alpha)>-1
$$

and, for every fixed $\alpha$, let $F(t)$ be the function

$$
F(t)=\int_{0}^{\infty} x^{\alpha} \exp (q(t x)) f(x) d x, \quad t>0 .
$$

If $\lim _{x \rightarrow \infty} f(x)=A$ then $\lim _{t \rightarrow 0^{+}} t^{\alpha+1} F(t)=A H(\alpha)$.
Proof.

$$
H(\alpha)=\int_{0}^{\infty} x^{\alpha} \exp (q(x)) d x=\int_{0}^{\infty}(t x)^{\alpha} \exp (q(t x)) t d x, \quad t>0 .
$$

For a given $\varepsilon>0$, let $T$ be such that $|f(x)-A|<\varepsilon$ for $x>T$. Then

$$
\begin{aligned}
\left|t^{\alpha+1} F(t)-A H(\alpha)\right|= & \left|t^{\alpha+1} \int_{0}^{\infty} x^{\alpha} \exp (q(t x))(f(x)-A) d x\right| \\
\leqslant & \left|t^{\alpha+1}\right| \int_{0}^{T}\left|x^{\alpha} \exp (q(t x))\right||f(x)-A| d x \\
& +\varepsilon \int_{T}^{\infty}\left|x^{\alpha} \exp (q(t x)) t^{\alpha+1}\right| d x \\
\leqslant & \left|t^{\alpha+1}\right| T M+\varepsilon \int_{0}^{\infty}\left|x^{\alpha} \exp (q(x))\right| d x
\end{aligned}
$$

where $M$ is an upper bound of the function $\left|x^{\alpha} \exp (q(t x))\right||f(x)-A|$ for $x \in[0, T]$ and $t \in\left[0, t_{0}\right]$ for some fixed $t_{0}$. Hence

$$
\lim _{t \rightarrow 0^{+}}\left|t^{\alpha+1} F(t)-A H(\alpha)\right| \leqslant \varepsilon \int_{0}^{\infty}\left|x^{\alpha} \exp (q(x))\right| d x
$$

and $\lim _{t \rightarrow 0^{+}} t^{\alpha+1} F(t)=A H(\alpha)$ follows.
Proof of the Theorem. (I) First, we consider the particular case

$$
D(x L)+\left((s+1) x^{s+1}+\cdots\right) L=0 .
$$

The only paths now are from zero to infinity, so we simplify notation

$$
\left\langle L_{j}, p\right\rangle=\int_{\gamma_{j}} p(z) w(z) d z, \quad j=1, \ldots, s+1,
$$

where

$$
\begin{aligned}
& \gamma_{j} \equiv \beta_{j} x, \quad 0 \leqslant x<\infty, \quad \beta_{j}^{s+1}=1, \quad \text { and } \\
& w(z)=z^{\alpha} \exp \left(-z^{s+1}+q(z)\right), \quad \operatorname{deg} q \leqslant s .
\end{aligned}
$$

If $\sum_{j=1}^{s+1} \lambda_{j} L_{j}=0$ then

$$
\begin{equation*}
\left\langle\sum_{j=1}^{s+1} \lambda_{j} L_{j}, z^{n(s+1)+k}\right\rangle=0 ; \quad k=0, \ldots, s ; \quad n=0,1, \ldots \tag{10}
\end{equation*}
$$

## Since

$$
\begin{aligned}
\left\langle L_{j},\right. & \left.z^{n(s+1)+k}\right\rangle \\
& =\int_{0}^{\infty} x^{n(s+1)+k+\alpha} \beta_{j}^{\alpha+k+1} \exp \left(-x^{s+1}+q\left(\beta_{j} x\right)\right) d x \\
& =\frac{1}{s+1} \int_{0}^{\infty} \exp (-t) t^{n+(k+\alpha-s) /(s+1)} \beta_{j}^{\alpha+k+1} \exp \left(q\left(\beta_{j} t^{1 /(s+1)}\right)\right) d t
\end{aligned}
$$

for each fixed $k$, (10) becomes

$$
\begin{aligned}
0 & =\frac{1}{s+1} \int_{0}^{\infty} \exp (-t) t^{n+(k+\alpha-s) /(s+1)} \sum_{j=1}^{s+1} \lambda_{j} \beta_{j}^{\alpha+k+1} \exp \left(q\left(\beta_{j} t^{1 /(s+1)}\right)\right) d t \\
& =\frac{1}{s+1}(-1)^{n} F_{k}^{(n)}(1), \quad n=0,1, \ldots
\end{aligned}
$$

where $F_{k}(y)$ is the Laplace transform of

$$
t^{(k+\alpha-s) /(s+1)} \sum_{j=1}^{s+1} \lambda_{j} \beta_{j}^{\alpha+k+1} \exp \left(q\left(\beta_{j} t^{1 /(s+1)}\right)\right) .
$$

As a consequence $F_{k}(y)=0$ and

$$
\sum_{j=1}^{s+1} \lambda_{j} \beta_{j}^{\alpha+k+1} \exp \left(q\left(\beta_{j} t^{1 /(s+1)}\right)\right)=0, \quad k=0, \ldots, s
$$

follows. Since $\operatorname{det}\left(\beta_{j}^{\alpha+k+1}\right)_{j=1, k=0}^{s+1, s} \neq 0$, we have

$$
\lambda_{j} \exp \left(q\left(\beta_{j} 1^{1 /(s+1)}\right)\right)=0, \quad j=1, \ldots, s+1
$$

from which $\lambda_{j}=0, j=1, \ldots, s+1$, and $\left\{L_{1}, \ldots, L_{s+1}\right\}$ is an FSS.
(II) General case. Now we write $w(z)=z^{\alpha_{0}} \prod_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \times$ $\exp (q(z)) f(z)$ and suppose

$$
\begin{equation*}
\sum_{m=1}^{s-N+1} \lambda_{m} L_{m}+\sum_{k=0}^{M} \sum_{j=1}^{r_{k}} \lambda_{k, j} L_{k, j}+\sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}=0 \tag{11}
\end{equation*}
$$

Then

$$
\begin{align*}
\sum_{m=1}^{s-N+1} & \lambda_{m} \int_{R_{m}} w(z) p(z) d z \\
= & -\sum_{k=0}^{M} \sum_{j=1}^{r_{k}} \lambda_{k, j} \int_{\Gamma_{k, j}} p(z) w(z) d z-\sum_{k=1}^{M} \lambda_{k}^{*} \int_{E_{k}} p(z) w(z) d z \\
& -\sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{0} \cup C_{m}} p(z) w(z) d z \quad \text { for every polynomial } p(z) . \tag{12}
\end{align*}
$$

Let $\mu$ be a positive integer such that $\mathfrak{R}\left(\alpha_{0}+\cdots+\alpha_{k}+\mu\right)>-1$, let

$$
\begin{aligned}
F_{p}(t)= & \sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{m}} z^{p+\alpha_{0}+\mu} \prod_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \exp (q(t z)) f(z) d z \\
= & \sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{m}} z^{p+\alpha_{0}+\cdots+\alpha_{M}+\mu} \\
& \times \prod_{k=1}^{m}\left(1-\frac{a_{k}}{z}\right)^{\alpha_{k}} \exp (q(t z)) f(z) d z, \quad p=0, \ldots, s-N,
\end{aligned}
$$

and

$$
\begin{aligned}
G_{p}(t)= & -\sum_{k=0}^{M} \sum_{j=1}^{r_{k}} \lambda_{k, j} \int_{\Gamma_{k, j}} z^{p+\alpha_{0}+\mu} \prod_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \exp (q(t z)) f(z) d z \\
& -\sum_{k=1}^{M} \lambda_{k}^{*} \int_{E_{k}} z^{p+\alpha_{0}+\mu} \prod_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \exp (q(t z)) f(z) d z \\
& -\sum_{m=1}^{s-N+1} \lambda_{m} \int_{R_{0} \cup C_{m}} z^{p+\alpha_{0}+\mu} \prod_{k=1}^{M}\left(z-a_{k}\right)^{\alpha_{k}} \exp (q(t z)) f(z) d z, \\
& \quad p=0, \ldots, s-N .
\end{aligned}
$$

$F_{p}(t)$ is an analytic function in $\mathfrak{R}\left(t^{s-N+1}\right)>0$ and so is $G_{p}(t)$ in the whole complex plane. From (12), $F_{p}^{(n)}(1)=G_{p}^{(n)}(1), n=0,1, \ldots$ and $F_{p}(t)=G_{p}(t)$, $t \in \mathfrak{R}\left(t^{s-N+1}\right)>0$, follows for $p=0, \ldots, s-N$. As a consequence

$$
\begin{aligned}
& \lim _{t \rightarrow 0^{+}} t^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p+1} F_{p}(t) \\
& \quad=\lim _{t \rightarrow 0^{+}} t^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p+1} G_{p}(t)=0, \quad p=0, \ldots, s-N .
\end{aligned}
$$

Moreover,

$$
\begin{aligned}
F_{p}(t)= & \sum_{m=1}^{s-N+1} \lambda_{m} \int_{l_{0}^{*}}^{\infty}\left(\beta_{m} x\right)^{p+\alpha_{0}+\cdots+\alpha_{M}+\mu} \\
& \times \prod_{k=1}^{M}\left(1-\frac{a_{k}}{\beta_{m} x}\right)^{\alpha_{k}} \exp \left(q\left(t \beta_{m} x\right)\right) f\left(\beta_{m} x\right) \beta_{m} d x \\
= & \sum_{m=1}^{s-N+1} \lambda_{m} \int_{0}^{\infty}\left(\beta_{m} x\right)^{p+\alpha_{0}+\cdots+\alpha_{M}+\mu} \\
& \times \prod_{k=1}^{M}\left(1-\frac{a_{k}}{\beta_{m} x}\right)^{\alpha_{k}} \exp \left(q\left(t \beta_{m} x\right)\right) f\left(\beta_{m} x\right) \beta_{m} \chi_{\left[l_{0}^{*}, \infty\right]}(x) d x,
\end{aligned}
$$

where $\chi_{\left[L_{0}^{*}, \infty\right)}(x)=1$ when $x \in\left[l_{0}^{*}, \infty\right)$ and zero otherwise.
Since $\exp \left(\beta_{m} x\right)=\exp \left(-x^{s-N+1}+\cdots\right)$, we can apply Lemma 2.2 to each term in the expression of $F_{p}(t)$ and obtain

$$
\begin{aligned}
0 & =\lim _{t \rightarrow 0^{+}} t^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p+1} F_{p}(t) \\
& =\sum_{m=1}^{s-N+1} \lambda_{m} \beta_{m}^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p+1} \int_{0}^{\infty} x^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p} \exp \left(q\left(\beta_{m} x\right)\right) d x
\end{aligned}
$$

for $p=0, \ldots, s-N$, because $\lim _{x \rightarrow \infty} \prod_{k=1}^{M}\left(1-\left(a_{k} / \beta_{m} x\right)\right)^{\alpha_{k}} f\left(\beta_{m} x\right)=1$, $m=1, \ldots, s-N+1$. This system is the same as

$$
0=\sum_{m=1}^{s-N+1} \lambda_{m} \int_{\delta_{m}} z^{\alpha_{0}+\cdots+\alpha_{M}+\mu+p} \exp (q(z)) d z, \quad p=0, \ldots, s-N,
$$

where $\delta_{m}$ is the line $z=\beta_{m} x, 0 \leqslant x<\infty$, and its determinant may be written in the form

$$
\operatorname{det}\left(\left\langle\bar{L}_{m}, z^{p}\right\rangle\right)_{m=1, p=0}^{s-N+1, s-N},
$$

where $\left\{\bar{L}_{1}, \ldots, \bar{L}_{s-N+1}\right\}$ is an FSS for

$$
D(x L)-\left(x q^{\prime}(x)+\alpha+1\right) L=0, \quad \alpha=\alpha_{0}+\cdots+\alpha_{M}+\mu,
$$

as was proved for the particular case of part (I). Taking into account Lemma 2.1, this determinant is non-zero and $\lambda_{m}=0, m=1, \ldots, s-N+1$ follows.

Equation (11) becomes

$$
\begin{equation*}
\sum_{k=0}^{M} \sum_{j=1}^{r_{k}} \lambda_{k, j} L_{k, j}+\sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}=0 \tag{13}
\end{equation*}
$$

Suppose that some $a_{k}$, and therefore $a_{0}(=0)$ is a multiple zero; otherwise there is nothing to prove with respect to $\lambda_{k, j}$. It will be proved that $\lambda_{0, j}=0, j=1, \ldots, r_{0}$.

From (13) it follows that

$$
\begin{align*}
& \left\langle\sum_{j=1}^{r_{0}} \lambda_{0, j} L_{0, j}, z^{n r_{0}+p}\right\rangle+\left\langle\sum_{k \neq 0} \sum_{j=1}^{r_{k}} \lambda_{k, j} L_{k, j}, z^{n r_{0}+p}\right\rangle \\
& \quad+\left\langle\sum_{j=1}^{M} \lambda_{k}^{*} L_{k}^{*}, z^{n r_{0}+p}\right\rangle=0, \quad p=0, \ldots, r_{0}-1, \quad n=0,1, \ldots . \tag{14}
\end{align*}
$$

Now we write $w(z)=z^{\alpha_{0}} \exp \left(-1 / z^{r_{0}}\right) g(z)$. Since $\beta_{0,1}, \ldots, \beta_{0, r_{0}}$, are the $r_{0}$-roots of the unity, we have

$$
\begin{aligned}
& \left\langle\sum_{j=1}^{r_{0}} \lambda_{0, j} L_{0, j}, z^{n r_{0}+p}\right\rangle \\
& \quad=\sum_{j=1}^{r_{0}} \lambda_{0, j} \int_{\Gamma_{0, j}} z^{n r_{0}+p+\alpha_{0}} \exp \left(\frac{-1}{z^{r_{0}}}\right) g(z) d z \\
& \quad=\int_{\Gamma_{0,1}} z^{n r_{0}+p+\alpha_{0}} \exp \left(\frac{-1}{t}\right) \sum_{j=1}^{r_{0}} \lambda_{0, j} \beta_{0, j}^{p+\alpha_{0}+1} g\left(z \beta_{0, j}\right) d z
\end{aligned}
$$

and, letting $z^{r_{0}}=t$, the above equation reduces to

$$
\frac{1}{r_{0}} \int_{\Gamma} t^{n} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}+1-r_{0}\right) / r_{0}} \sum_{j=1}^{r_{0}} \lambda_{0, j} \beta_{0, j}^{\alpha_{0}+p+1} g\left(t^{1 / r_{0}} \beta_{0, j}\right) d t
$$

where $\Gamma$ is the path in Fig. 2. On the other hand, after making the substitution $z^{r_{0}}=t$, we also have

$$
\begin{aligned}
& \left\langle\sum_{k \neq 0} \sum_{j=1}^{r_{k}} \lambda_{k, j} L_{k, j}, z^{n r_{0}+p}\right\rangle \\
& =\frac{1}{r_{0}} \sum_{k \neq 0} \sum_{j=1}^{r_{k}} \lambda_{k, j} \int_{\bar{\Gamma}_{k, j}} t^{n} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} g\left(t^{1 / r_{0}}\right) d t, \\
& \quad p=0, \ldots, r_{0}-1, \quad n=0,1, \ldots,
\end{aligned}
$$

where $\bar{\Gamma}_{k, j}$ is a curve in the region $|t|>l_{0}^{r_{0}}$. Furthermore

$$
\begin{aligned}
& \left\langle\sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}, z^{n r_{0}+p}\right\rangle \\
& =\frac{1}{r_{0}} \sum_{k=1}^{M} \lambda_{k}^{*} \int_{\bar{E}_{k}} t^{n} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} g\left(t^{1 / r_{0}}\right) d t, \\
& \quad p=0, \ldots, r_{0}-1, \quad n=0,1, \ldots,
\end{aligned}
$$

## $\Gamma \equiv$



FIGURE 2
where $\bar{E}_{k}$ is a curve such that its part near zero is in the region $\mathfrak{\Re}(t)>0$, and the corresponding integral converges.

Hence, from (14) it follows that

$$
\begin{aligned}
& \int_{\Gamma} \frac{1}{t-\zeta} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha-r_{0}+1\right) / r_{0}} \sum_{j=1}^{r_{0}} \lambda_{0, j} \beta_{0, j}^{\alpha_{0}+p+1} g\left(t^{1 / r_{0}} \beta_{0, j}\right) d t \\
& \quad+\sum_{k \neq 0} \sum_{j=1}^{r_{k}} \lambda_{k, j} \int_{\bar{\Gamma}_{k, j}} \frac{1}{t-\zeta} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} g\left(t^{1 / r_{0}}\right) d t \\
& \quad+\sum_{k=1}^{M} \lambda_{k}^{*} \int_{\bar{E}_{k}} \frac{1}{t-\zeta} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} g\left(t^{1 / r_{0}}\right) d t=0
\end{aligned}
$$

for $\zeta$ such that $|\zeta|$ is large enough and for each $p=0, \ldots, r_{0}-1$. With $p$ fixed and denoting each term in the last expression in $H_{1}(\zeta), H_{2}(\zeta)$, and $H_{3}(\zeta)$, it becomes

$$
H_{1}(\zeta)+H_{2}(\zeta)+H_{3}(\zeta)=0 \quad \text { for }|\zeta| \text { sufficiently large. }
$$

For $\varepsilon>0$, if we use $H_{1, \varepsilon}(\zeta)$ to refer to the integral of the function which defines $H_{1}(\zeta)$ but now over the path $\Gamma_{\varepsilon}$ of Fig. 3, we have $H_{1}(\zeta)=H_{1, \varepsilon}(\zeta)$ when $|\zeta|>l_{0}^{r_{0}}$, whence

$$
H_{1, \varepsilon}(\zeta)+H_{2}(\zeta)+H_{3}(\zeta)=0
$$

for $|\zeta|>\varepsilon$ and $\zeta$ outside the curves $\bar{\Gamma}_{k, j}$ and $\bar{E}_{k}$.
Let $C$ be the curve in Fig. 4 and let $\zeta$ be a point such that $\varepsilon<|\zeta|<l_{0}^{r_{0}}$ and $\zeta \notin\left(\varepsilon, l_{0}^{r_{0}}\right)$. By Cauchy's theorem we have


FIGURE 3


FIGURE 4

$$
\begin{align*}
& 2 \pi i \exp \left(\frac{-1}{\zeta}\right) \zeta^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} \sum_{j=1}^{r_{0}} \lambda_{0, j}{\beta_{0, j}^{\alpha_{0}+p+1} g\left(\zeta^{1 / r_{0}} \beta_{0, j}\right)}_{\quad=\int_{C} \frac{1}{t-\zeta} \exp \left(\frac{-1}{t}\right) t^{\left(p+\alpha_{0}-r_{0}+1\right) / r_{0}} \sum_{j=1}^{r_{0}} \lambda_{0, j} \beta_{0, j}^{\alpha_{0}+p+1} g\left(t^{1 / r_{0}} \beta_{0, j}\right) d t}^{\quad=H_{1}(\zeta)-H_{1, \varepsilon}(\zeta)=H_{1}(\zeta)+H_{2}(\zeta)+H_{3}(\zeta)}
\end{align*}
$$

Let $\zeta$ be a point in $\left(-\frac{1}{2}, 0\right)$. Then $|t-\zeta| \geqslant t$ when $t \in\left[0, l_{0}^{r_{0}}\right]$, and $|t-\zeta| \geqslant \frac{1}{2}$ when $t$ lies in $|t|=l_{0}^{r_{0}}$. Therefore $H_{1}(\zeta)$ is a bounded function when $\zeta \in\left(-\frac{1}{2}, 0\right)$. Moreover, $H_{2}(\zeta)$ and $H_{3}(\zeta)$ are bounded too in the same region. As a consequence, equality (15) only holds when

$$
\sum_{j=1}^{r_{0}} \lambda_{0, j} \beta_{0, j}^{\alpha_{0}+p+1} g\left(\zeta^{1 / r_{0}} \beta_{0, j}\right)=0, \quad p=0, \ldots, r_{0}-1
$$

from which $\lambda_{0, j}=0, j=1, \ldots, r_{0}$.
It is clear that the preceding work can be carried over to any multiple zero $a_{k}$ by a change $z-a_{k}=t$. Hence $\lambda_{k, j}=0, j=1, \ldots, r_{k}$, for every $k$ such that $a_{k}$ is a multiple zero. It remains to be proved that $\lambda_{k}^{*}=0$ for $k=1, \ldots, M$.

$$
\left\langle\sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}, p\right\rangle=\sum_{k=1}^{M} \lambda_{k}^{*} \int_{E_{k}} w(z) p(z) d z=\int_{X} w(z) \sum_{k=1}^{M} \lambda_{k}^{*} \chi_{E_{k}}(z) p(z) d z
$$

where $X=\bigcup_{k=1}^{M} E_{k}$, and $\chi_{E_{k}}(z)=1$ when $z \in E_{k}$ and zero otherwise. It is clear that this is a bounded functional over the space of continuous functions on $X$ and, since the complement of $X$ is connected and its interior is empty, by Merguelian's theorem, there exists only one extension of the functional over the continuous functions on $X$. Then, if

$$
\left\langle\sum_{k=1}^{M} \lambda_{k}^{*} L_{k}^{*}, p\right\rangle=0, \quad \text { for every polynomial } p
$$

it is zero on the continuous functions. Hence, from Riesz Representation Theorem, this functional may be represented in a unique form and it follows that

$$
w(z) \sum_{k=1}^{M} \lambda_{k}^{*} \chi_{E_{k}}(z)=0
$$

for every $z$ where this is a continuous function. Then $\lambda_{k}^{*}=0$ for $k=1, \ldots, M$.

## 3. REGULARIZATION

When $\mathfrak{R}\left(\alpha_{k}\right) \leqslant-1$ for some simple zero $a_{k}$, the corresponding integrals are not convergent and a regularization is needed. It will be done recurrently over the integer part of $\mathfrak{R}\left(\alpha_{k}\right)$.

Given the equation $D(\phi L)+\psi L=0$, if $a$ is a zero of $\phi$ we denote

$$
\phi(x)=(x-a) \phi_{a}(x), \quad \psi(x)=(x-a) \psi_{a}(x)+\psi(a),
$$

and, using Maroni's techniques, we consider

$$
\left\langle(x-a)^{-1} L, p\right\rangle=\left\langle L, \frac{p(x)-p(a)}{x-a}\right\rangle .
$$

Proposition 3.1. Let $a$ be one zero of $\phi$ such that $\psi(a) \neq 0$. If $\left\{L_{1}, \ldots, L_{s+1}\right\}$ is an FSS of the equation of class s and type (B)

$$
D(\phi L)+\left(\psi-\phi_{a}\right) L=0,
$$

then

$$
\left\{(x-a)^{-1} L_{1}+M_{1} \delta(x-a), \ldots,(x-a)^{-1} L_{s+1}+M_{s+1} \delta(x-a)\right\},
$$

where $M_{j}=-\left\langle L_{j}, \psi_{a}\right\rangle / \psi(a)$, is an FSS of $D(\phi L)+\psi L=0$.
Proof. Let $L_{j}^{*}=(x-a)^{-1} L_{j}+M_{j} \delta(x-a)$, then $L_{j}=(x-a) L_{j}^{*}$. Furthermore

$$
D\left((x-a)^{2} \phi_{a} L_{j}^{*}\right)=D\left((x-a) \phi_{a} L_{j}\right)=-\left(\psi-\phi_{a}\right) L_{j}
$$

and thus

$$
D\left((x-a)^{2} \phi_{a} L_{j}^{*}\right)+(x-a)\left(\psi-\phi_{a}\right) L_{j}^{*}=0 .
$$

Taking the derivative, we obtain $(x-a)\left(D\left(\phi L_{j}^{*}\right)+\psi L_{j}^{*}\right)=0$, which means that

$$
D\left(\phi L_{j}^{*}\right)+\psi L_{j}^{*}=\left\langle L_{j}^{*}, \psi\right\rangle \delta(x-a) .
$$

Moreover

$$
\begin{aligned}
\left\langle L_{j}^{*}, \psi\right\rangle & =\left\langle L_{j}, \frac{\psi(x)-\psi(a)}{x-a}\right\rangle+M_{j}\langle\delta(x-a), \psi\rangle \\
& =\left\langle L_{j}, \psi_{a}\right\rangle+M_{j} \psi(a)=0
\end{aligned}
$$

from the definition of $M_{j}$, and it follows that $D\left(\phi L_{j}^{*}\right)+\psi L_{j}^{*}=0$.
On the other hand

$$
\begin{aligned}
& \left\langle\begin{array}{ccc}
\left\langle L_{1}^{*}, 1\right\rangle, & \cdot & ,\left\langle L_{s+1}^{*}, 1\right\rangle \\
\left\langle L_{1}^{*}, x-a\right\rangle, & \cdot & ,\left\langle L_{s+1}^{*}, x-a\right\rangle \\
\vdots & \vdots & \vdots \\
\left\langle L_{1}^{*},(x-a)^{s}\right\rangle, & \cdot & ,\left\langle L_{s+1}^{*},(x-a)^{s}\right\rangle
\end{array}\right| \\
& =\left|\begin{array}{ccc}
M_{1}, & \cdot & , M_{s+1} \\
\left\langle L_{1}, 1\right\rangle, & \cdot & ,\left\langle L_{s+1}, 1\right\rangle \\
\vdots & \vdots & \vdots \\
\left\langle L_{1},(x-a)^{s-1}\right\rangle, & \cdot & ,\left\langle L_{s+1},(x-a)^{s-1}\right\rangle
\end{array}\right| \\
& =-\frac{K}{\psi(a)}\left|\begin{array}{ccc}
\left\langle L_{1},(x-a)^{s}\right\rangle, & \cdot & ,\left\langle L_{s+1},(x-a)^{s}\right\rangle \\
\left\langle L_{1}, 1\right\rangle, & \cdot & ,\left\langle L_{s+1}, 1\right\rangle \\
\vdots & \vdots & \vdots \\
\left\langle L_{1},(x-a)^{s-1}\right\rangle, & ,\left\langle L_{s+1},(x-a)^{s-1}\right\rangle
\end{array}\right|,
\end{aligned}
$$

where $K$ is the coefficient of degree $s+1$ of $\psi$ which is non-zero because the equation is of type (B). The last identity holds because the remaining terms in the first row are a linear combination of the others. By hypothesis $\left\{L_{1}, \ldots, L_{s+1}\right\}$ is an FSS and, from Lemma 2.1, the last determinant is nonzero. This means that $\left\{L_{1}^{*}, \ldots, L_{s+1}^{*}\right\}$ is an FSS of $D(\phi L)+\psi L=0$. Let us now explain the recursive process.

Suppose initially that only one $\alpha_{k}$ corresponding to a simple zero $a_{k}$ has $\mathfrak{R}\left(\alpha_{k}\right) \leqslant-1$ and that $\alpha_{k} \neq-1,-2, \ldots$. If $-2<\mathfrak{R}\left(\alpha_{k}\right) \leqslant-1$, equation $D(\phi L)+\left(\psi-\phi_{a_{k}}\right) L=0$ is covered by Theorem 2.1 because

$$
\frac{w^{\prime}(z)}{w(z)}=-\frac{\psi(z)-\phi_{a_{k}}(z)+\phi^{\prime}(z)}{\phi(z)}=-\frac{\psi(z)+\phi^{\prime}(z)}{\phi(z)}+\frac{1}{z-a_{k}} .
$$

By applying Proposition 3.1 we obtain the solution for $D(\phi L)+\psi L=0$. In order to apply Proposition 3.1 we need $\psi\left(a_{k}\right) \neq 0$, but this is equivalent to the condition $\alpha_{k} \neq-1$ because $a_{k}$ is a simple zero. By repeating the above process as many times as required by the integer part of $\mathfrak{R}\left(\alpha_{k}\right)$, we have the solution for case $\mathfrak{\Re}\left(\alpha_{k}\right) \leqslant-1$ provided that $\alpha_{k} \neq-1,-2, \ldots$.

Let us now solve case $\alpha_{k}=-1$, the solution of which can be extended with Proposition 3.1 to obtain the solution for $\alpha_{k}=-2,-3, \ldots$.

Proposition 3.2. Given the equation $D(\phi L)+\psi L=0$, suppose that, for some zero a of $\phi, \psi(a)=0$. Let $\left\{L_{1}, \ldots, L_{s}\right\}$ be an FSS of the equation of class $s-1, D\left(\phi_{a} L\right)+\psi_{a} L=0$. Then

$$
\left\{\delta(x-a),(x-a)^{-1} L_{1}, \ldots,(x-a)^{-1} L_{s}\right\}
$$

is an FSS of $D(\phi L)+\psi L=0$.
Proof. It is straightforward to show that $\delta(x-a)$ is a solution. Let $L_{j}^{*}=(x-a)^{-1} L_{j}$. Then $L_{j}=(x-a) L_{j}^{*}$, and it follows that

$$
D\left((x-a) \phi_{a} L_{j}^{*}\right)=D\left(\phi_{a} L_{j}\right)=-\psi_{a} L_{j}=-(x-a) \psi_{a} L_{j}^{*}=-\psi L_{j}^{*} .
$$

Moreover

$$
\begin{aligned}
& \left|\begin{array}{ccc}
\langle\delta(x-a), 1\rangle, & \cdot & \left\langle\delta(x-a),(x-a)^{s}\right\rangle \\
\left\langle L_{1}^{*}, 1\right\rangle, & \cdot & \left\langle L_{1}^{*},(x-a)^{s}\right\rangle \\
\vdots & \vdots & \vdots \\
\left\langle L_{s}^{*}, 1\right\rangle, & \cdot & \left\langle L_{s}^{*},(x-a)^{s}\right\rangle
\end{array}\right| \\
& \quad=\left|\begin{array}{cccc}
1 & 0 & \cdot & 0 \\
0 & \left\langle L_{1}, 1\right\rangle & \cdot & \left\langle L_{1},(x-a)^{s-1}\right\rangle \\
\vdots & \vdots & \vdots & \vdots \\
0 & \left\langle L_{s}, 1\right\rangle & \cdot & \left\langle L_{s},(x-a)^{s-1}\right\rangle
\end{array}\right|
\end{aligned}
$$

which is non-zero because $\left\{L_{1}, \ldots, L_{s}\right\}$ is an FSS. Hence $\{\delta(x-a)$, $\left.(x-a)^{-1} L_{1}, \ldots,(x-a)^{-1} L_{s}\right\}$ is an FSS of $D(\phi L)+\psi L=0$.

The equation $D\left(\phi_{a} L\right)+\psi_{a} L=0$, when regularization is necessary for only one zero, gives rise to two possibilities:
(1) The solution of the equation is covered by Theorem 2.1
(2) The equation reduces to $D L+K L=0$ where $K \neq 0$ is a constant.

The equation in case (2) yields

$$
\left\{\begin{array}{l}
K\langle L, 1\rangle=0 \\
-n\left\langle L, x^{n-1}\right\rangle+K\left\langle L, x^{n}\right\rangle=0, \quad n \geqslant 1,
\end{array}\right.
$$

and $\left\langle L, x^{n}\right\rangle=0, n \geqslant 0$, so $L=0$.
Thus, the equation is solved when only one zero has its real part less than or equal to -1 . If there were more than one zero with the real part less than or equal to -1 , Propositions 3.1 and 3.2 could be used to reduce this case to the previous case.

Example. We present an example of the regularization method for a semiclassical functional of class $s=N-1$ which covers Laguerre functionals ( $N=1$ ), studied by Morton and Krall in [16], and an example of Airy $(N=3)$ and Freud functionals $(N=4)$. Examples of Airy functionals may be seen in [12] and for Freud ones see, for example, [1].

Let $L$ be such that

$$
D(x L)+\left(N x^{N}-\alpha-1\right) L=0 .
$$

One of the solutions is, for $\mathfrak{R} \alpha>-1$,

$$
\left\langle L^{(\alpha)}, p\right\rangle=\int_{0}^{\infty} x^{\alpha} e^{-x^{N}} p(x) d x .
$$

Let us consider a real number $\varepsilon$ such that $-1<\varepsilon<0$. Our aim is to obtain the solution for $\alpha=\varepsilon-1, \varepsilon-2, \ldots, \varepsilon-n, \ldots$. From Proposition 3.1, the corresponding solution of

$$
D(x L)+\left(N x^{N}-(\varepsilon-n)-1\right) L=0
$$

can be written as

$$
L^{(\varepsilon-n)}=x^{-1} L^{(\varepsilon-n+1)}+M_{n} \delta,
$$

where

$$
M_{n}=\frac{\left\langle L^{(\varepsilon-n+1)}, N x^{N-1}\right\rangle}{\varepsilon+1-n} .
$$

With the same notation and using induction we get

$$
\begin{equation*}
L^{(\varepsilon-n)}=x^{-n} L^{(\varepsilon)}+\sum_{k=1}^{n} \frac{(-1)^{n-k}}{(n-k)!} M_{k} \delta^{(n-k)}, \tag{16}
\end{equation*}
$$

where

$$
\begin{aligned}
\left\langle x^{-n} L^{(\varepsilon)}, p\right\rangle & =\left\langle L^{(\varepsilon)}, \frac{1}{x^{n}}\left(p(x)-\sum_{j=0}^{n-1} \frac{p^{(j)}(0)}{j!} x^{j}\right)\right\rangle \\
& =\int_{0}^{\infty} x^{\varepsilon-n} e^{-x^{N}}\left\{p(x)-\sum_{j=0}^{n-1} \frac{p^{(j)}(0)}{j!} x^{j}\right\} d x
\end{aligned}
$$

and the derivatives of $\delta$ appear in (6) because $x^{-k} \delta=\left((-1)^{k} / k!\right) \delta^{(k)}$. So, we have to obtain $M_{k}, k=1, \ldots, n$.

Setting $k=v N+j, j=1, \ldots, N, v=1,2, \ldots$, we have

$$
\begin{aligned}
M_{v N+j} & =\frac{\left\langle L^{(\varepsilon-v N-j+1)}, N x^{N-1}\right\rangle}{\varepsilon+1-(v N+j)} \\
& =\frac{N}{\varepsilon+1-(v N+j)}\left\langle x^{-1} L^{(\varepsilon-v N-j+2)}+M_{v N+j} \delta, x^{N-1}\right\rangle \\
& =\frac{N}{\varepsilon+1-(v N+j)}\left\langle L^{(\varepsilon-v N-j+N)}, 1\right\rangle \\
& =\frac{N}{\varepsilon+1-(v N+j)}\left\langle x^{-1} L^{(\varepsilon-(v-1) N-j+1)}+M_{(v-1) N+j} \delta, 1\right\rangle \\
& =\frac{N}{\varepsilon+1-(v N+j)} M_{(v-1) N+j}
\end{aligned}
$$

As a consequence, for $j=1, \ldots, N$ and $v=0,1, \ldots$, we have

$$
\begin{equation*}
M_{v N+j}=\frac{N}{\varepsilon+1-(v N+j)} \frac{N}{\varepsilon+1-((v-1) N+j)} \cdots \frac{N}{\varepsilon+1-j}\left\langle L^{(\varepsilon)}, x^{N-j}\right\rangle \tag{17}
\end{equation*}
$$

because

$$
M_{j}=\frac{N}{\varepsilon+1-j}\left\langle L^{(\varepsilon)}, x^{N-j}\right\rangle, \quad j=1, \ldots, N
$$

Hence, letting $M_{v N+j}=A_{v N+j}\left\langle L^{(\varepsilon)}, x^{N-j}\right\rangle$, and $n=k N+r, r=1, \ldots, N$, expression (17) in (16) yields

$$
\begin{aligned}
&\left\langle L^{(\varepsilon-k N-r)}, p\right\rangle \\
&=\left\langle x^{-(k N+r)} L^{(\varepsilon)}, p\right\rangle+\sum_{v=0}^{k-1} \sum_{j=1}^{N} \frac{A_{v N+j} p^{(k-v) N+r-j}(0)}{((k-v) N+r-j)!}\left\langle L^{(\varepsilon)}, x^{N-j}\right\rangle \\
&+\sum_{j=1}^{r} \frac{A_{k N+j} p^{(r-j)}(0)}{(r-j)!}\left\langle L^{(\varepsilon)}, x^{N-j}\right\rangle .
\end{aligned}
$$

Then

$$
\begin{aligned}
\left\langle L^{(\varepsilon-k N-r)}, p\right\rangle= & \int_{0}^{\infty} x^{\varepsilon-k N-r} e^{-x^{N}}\left\{p(x)-\sum_{j=0}^{k N+r-1} \frac{p^{(j)}(0)}{j!} x^{j}\right. \\
& +\sum_{v=0}^{k-1} \sum_{j=1}^{N} \frac{A_{v N+j} p^{(k-v) N+r-j}(0)}{((k-v) N+r-j)!} x^{(k+1) N+r-j} \\
& \left.+\sum_{j=1}^{r} \frac{A_{k N+j} p^{(r-j)}(0)}{(r-j)!} x^{(k+1) N+r-j}\right\} d x
\end{aligned}
$$

and the $A_{v N+j}$ are defined by the recurrent relation

$$
\begin{aligned}
A_{j} & =\frac{N}{\varepsilon+1-j}, \quad j=1, \ldots, N \\
A_{v N+j} & =\frac{N}{\varepsilon+1-(v N+j)} A_{(v-1) N+j}, \quad j=1, \ldots, N ; v=1,2, \ldots
\end{aligned}
$$

In cases $\alpha=-1,-2, \ldots$, the solutions have a different form. For $\alpha=-1$, $D(x L)+N x^{N} L=0$, by Proposition 3.2 one must solve

$$
D L+N x^{N-1} L=0 .
$$

Any solution of this equation has the form

$$
\langle L, p\rangle=\sum_{i=1}^{N-1} \lambda_{i} \int_{\gamma_{i}} p(z) e^{-z^{N}} d z,
$$

where the $\gamma_{i}$ are defined in Theorem 2.1. Therefore, by Proposition 3.2, any solution $L_{N}^{(-1)}$ of $D(x L)+N x^{N} L=0$ may be written as

$$
\left\langle L_{N}^{(-1)}, p\right\rangle=\sum_{i=1}^{N-1} \lambda_{i} \int_{\gamma_{i}} \frac{p(z)-p(0)}{z} e^{-z^{N}} d z+\lambda_{N} p(0)
$$

and the corresponding solutions for $\alpha=-2,-3, \ldots$ must be obtained with Proposition 3.1 again. Letting

$$
\begin{aligned}
& \left\langle L_{N, i}^{(-1)}, p\right\rangle=\int_{\gamma_{i}} \frac{p(z)-p(0)}{z} e^{-z^{N}} d z, \quad i=1, \ldots, N-1, \\
& \left\langle L_{N, N}^{(-1)}, p\right\rangle=\langle\delta, p\rangle,
\end{aligned}
$$

in the same way as before, for $i=1, \ldots, N$ we have

$$
\begin{aligned}
\left\langle L_{N, i}^{(-1-k N-r)}, p\right\rangle= & \left\langle x^{-(k N+r)} L_{N, i}^{(-1)}, p\right\rangle \\
& +\sum_{v=0}^{k-1} \sum_{j=1}^{N} \frac{A_{v N+j} p^{(k-v) N+r-j}(0)}{((k-v) N+r-j)!}\left\langle L_{N, i}^{(-1)}, x^{N-j}\right\rangle \\
& +\sum_{j=1}^{r} \frac{A_{k N+j} p^{(r-j)}(0)}{(r-j)!}\left\langle L_{N, i}^{(-1)}, x^{N-j}\right\rangle,
\end{aligned}
$$

where

$$
\begin{aligned}
A_{j} & =-\frac{N}{j}, \quad j=1, \ldots, N \\
A_{v N+j} & =-\frac{N}{v N+j} A_{(v-1) N+j}, \quad j=1, \ldots, N ; v=1,2, \ldots
\end{aligned}
$$

Remark. Freud weights are explicitly related to this problem. In fact, the associated linear functional is a B-functional. The distributional equation allows us to obtain the nonlinear equations (the so-called Freud equations) of the coefficients of the three-term recurrence relation of the corresponding sequence of orthogonal polynomials. Furthermore, the solutions of such equations are given in terms of Hankel determinants whose entries are the moments $\left(\mu_{k}\right)$. They satisfy a linear recurrence relation as we pointed out in the Introduction. In a private communication, A. P. Magnus announced the connection between Freud equations and discrete Painlevé equations when $\phi=1$ and $\psi$ is an odd polynomial.

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[^0]:    ${ }^{1}$ From Carleman's criteria it follows that, for positive definite functionals on the real line, the problem of moments is determined.

